

Exploitable Results by Third Parties

14018 OpenCPS

Project details

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Name: OMSimulator		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Functional Mock-up Units (FMUs) ▪ and/or System Structure & Parameterizations (SSPs) ▪ and/or simulation models in third party tools 	<ul style="list-style-type: none"> ▪ Open source co-simulation tool for standardized, numerically robust, and efficient distributed simulation ▪ Supporting i) Functional Mock-up Interface (FMI) 2.0 CS & ME, ii) System, Structure & Parameterization (SSP), and iii) the Transmission Line element Method (TLM) ▪ Supports integration of FMUs as well as external tool integration, e.g. Simulink, Adams, Hopsan, Dymola 	<ul style="list-style-type: none"> ▪ Simulation results ▪ Composite model definition according to SSP
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Industry-grade and open-source model integration and co-simulation tool ▪ Combines the benefits of FMI, SSP, and TLM ▪ Integrated with GUI support in OpenModelica and Papyrus, and available as standalone for integration into scripting frameworks, third-party tools, and specialized applications 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Available for Windows and Linux platforms 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Industry and academia 	
Provider:	<ul style="list-style-type: none"> ▪ Open Source Modelica Consortium (OSMC) 	
Contact point:	<ul style="list-style-type: none"> ▪ Prof. Peter Fritzson (Linköping University) 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Open-source conditions according to OSMC: https://openmodelica.org/home/consortium 	

Latest update: 16 November 2018

Name: PhiSystem / Simulation module		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Functional Mock-up Units (FMUs) ▪ OMSimulator ▪ System architecture description (SysML) developed with the initial version of PhiSystem 	<ul style="list-style-type: none"> ▪ Simulation architecture definition ▪ Traceability between system and simulation architecture ▪ Subsystem model specification (purpose and I/O interface) ▪ FMUs integration ▪ Simulation execution and analysis 	<ul style="list-style-type: none"> ▪ Simulation results ▪ Link with system objectives and requirements via metrics assessment
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Available as standalone with PhiSystem ▪ Open-source license 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Availability of OMSimulator 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Industry and academia ▪ In industry: system architects and/or system designers 	
Provider:	<ul style="list-style-type: none"> ▪ Sherpa Engineering (www.sherpa-eng.com) 	
Contact point:	<ul style="list-style-type: none"> ▪ Philippe Fiani (p.fiani@sherpa-eng.com) 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Open-source conditions 	
<i>Latest update: 19 November 2018</i>		

Name: FMI Export module in Pro-SiVIC		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Autonomous driving scenario ▪ 3D scene ▪ Sensing configuration 	<ul style="list-style-type: none"> ▪ Selection of entities (sensors) to be exported ▪ Export of all perception sensors' data interface in an FMU ▪ Supporting Functional Mock-up Interface (FMI) 2.0 CS 	<ul style="list-style-type: none"> ▪ FMUs exposing Sensor Data outputs
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Availability of sensor's raw output to address perception performance issues ▪ Simulation can be executed on different machine than FMI model 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Windows platform. 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Car Manufacturers, Tier One and Tier Two suppliers developing or integrating Advanced Driver Assistance Systems (ADAS) and/or Autonomous Driving (AD) functions 	
Provider:	<ul style="list-style-type: none"> ▪ ESI Group 	
Contact point:	<ul style="list-style-type: none"> ▪ Rodolphe.Tchalekian@esi-group.com (EMEA Pro-SiVIC Business Developer) ▪ Philippe.DeSouza@esi-group.com (Pro-SiVIC Product Manager) 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Commercial Licenses (Yearly or Paid-up) ▪ Research Licenses (Yearly or Paid-up) 	
<i>Latest update: 20 November 2018</i>		

Name: txtUML		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Textual Model Code ▪ Deployment Configuration ▪ FMU Configuration 	<ul style="list-style-type: none"> ▪ Generation of UML2 model from textual model supporting wide variety of standard UML2 elements ▪ Automatic parallelization of classes based on deployment configuration ▪ Generation of standard FMU based on FMI configuration 	<ul style="list-style-type: none"> ▪ Model Adaptation in C++ ▪ Generated FMU environment ▪ FMU packaged according to standard
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Textual (VCS friendly) executable UML model ▪ Automatic generation of UML diagrams ▪ Live debug and testing through state machine and sequence diagrams 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Available for all platforms inside Eclipse ecosystem 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Industry and academia 	
Provider:	<ul style="list-style-type: none"> ▪ ELTE-Soft, Eötvös Loránd Science University, Budapest 	
Contact point:	<ul style="list-style-type: none"> ▪ Gera Zoltán, ELTE University: https://github.com/ELTE-Soft/txtUML 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Open-source with EPL-1.0 license: https://github.com/ELTE-Soft/txtUML/blob/master/LICENSE 	
<i>Latest update: 16 November 2018</i>		

Name: xtUML-Wrapper for FMI 2.0		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Functional Mock-up units (FMUs) designed and realized using Model Based Systems Engineering (MBSE) methodology ▪ Model and interface configuration files ▪ Simulation infrastructure that is compliant with the FMI 2.0 standard 	<ul style="list-style-type: none"> ▪ Provides a generic MBSE (xtUML) model of the FMI 2.0 standard that enables straight forward integration of non-FMI compliant MBSE-modelled simulation entities ▪ Integrates with any FMI-compliant simulation master ▪ Uses the xtUML methodology and tool set for modeling and generation of executables ▪ Provides the first working MBSE-model of the FMI 2.0 standard API 	<ul style="list-style-type: none"> ▪ An functional MBSE-model integrated in a running simulation environment ▪ Simulation results
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Provides integration of any xtUML-model with a simulation infrastructure supporting the FMI 2.0 standard API. ▪ Combines the benefit of FMI and MBSE (xtUML) 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Available for Windows and Linux platforms 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Industry and academia 	
Provider:	<ul style="list-style-type: none"> ▪ Saab AB 	
Contact point:	<ul style="list-style-type: none"> ▪ Ph.D. Nils Paulsson 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Commercial license to be negotiated, a free license can be provided for research purposes 	

Latest update: 22 November 2018

Name: SSP-FMU design extension for Papyrus		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Functional Mock-up Units (FMUs) ▪ and/or System Structure & Parameterizations (SSPs). ▪ OMSimulator for executing simulation. 	<ul style="list-style-type: none"> ▪ Open-source extension for Papyrus supporting the definition of complex simulation scenarios. ▪ Authoring tool for SSP descriptions that provides direct synchronization between SysML bbds and SSP. ▪ Scripting platform for defining multiple simulation scenarios and advanced visualization. 	<ul style="list-style-type: none"> ▪ Composite model definition according to current SSP standard. ▪ Simulation results
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Supporting round-trip engineering between SysML and SSP for architecture and simulation design ▪ High-level scripting support for defining complex simulation scenarios ▪ Advanced browser based result visualization based on Jupyter's notebook mechanism. 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Available on all platforms supporting Java 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Industry and academia 	
Provider:	<ul style="list-style-type: none"> ▪ CEA and IncQuery Labs as part of Eclipse Modeling Project 	
Contact point:	<ul style="list-style-type: none"> ▪ Sebastien Revol (CEA) 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Open source under EPL v2.0: https://www.eclipse.org/legal/epl-v20.html 	

Latest update: 29 November 2018

Name: Papyrus support of OMG Precise Semantics for State Machine (PSSM) standard		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> UML models containing State Machines complying to PSSM OMG standard 	<ul style="list-style-type: none"> Open Source simulation engine interpreting the state machines, fully aligned with OMG standard specifications Diagram animation support Debug support 	<ul style="list-style-type: none"> Simulation results
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Only Open Source tool providing a full support of the Object Management Group standard specification for model execution 	
Integration constraint(s):	<ul style="list-style-type: none"> Available on all platforms supporting Java 	
Intended user(s):	<ul style="list-style-type: none"> Industry and academia 	
Provider:	<ul style="list-style-type: none"> CEA as part of Eclipse Modeling Project 	
Contact point:	<ul style="list-style-type: none"> Jeremie Tatibouet (CEA) 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Open source under EPL v2.0: https://www.eclipse.org/legal/epl-v20.html 	
<i>Latest update: 29 November 2018</i>		

Name: Multi-Domain Modelica Models for Gas Turbine and Power Grid Analysis		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> Model parameters 	<ul style="list-style-type: none"> Modelica package for turbo-mechanical gas turbine models. Modelica package for power systems models Modelica package with examples and interfaces for multi-domain models 	<ul style="list-style-type: none"> Simulation results
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Gas turbine models – based on the ThermoPower library – are adapted to be used in combination with power system models, based on the OpenIPSL library. Suitable dynamic study of detailed network models with electrical and mechanical components. The library can be extended to other domains, eliciting the representation of power systems components with further details. 	
Integration constraint(s):	<ul style="list-style-type: none"> Dymola and OpenModelica (partial support) 	
Intended user(s):	<ul style="list-style-type: none"> Industry and academia 	
Provider:	<ul style="list-style-type: none"> Royal Institute of Technology (KTH) Rensselaer Polytechnic Institute (RPI) Instituto Costarricense de Electricidad (ICE) 	
Contact point:	<ul style="list-style-type: none"> Luigi Vanfretti (RPI), Miguel Aguilera (ICE) via: https://github.com/ALSETLab/2018_AmericanModelicaConf_PowerGrid_plus_PowerSystems 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Licensed under the GNU GPL v3 See terms under: https://github.com/ALSETLab/2018_AmericanModelicaConf_PowerGrid_plus_PowerSystems/blob/master/LICENSE 	
<i>Latest update: 30 November 2018</i>		

Name: IDA Software-in-the-loop simulator for PLC code		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ IEC 61131-3 PLC control code from the open source Beremiz authoring system ▪ Connections between the controller(s) and the physical system model 	<ul style="list-style-type: none"> ▪ Fast simulation of IEC 61131-3 PLC code coupled with IDA based simulators ▪ Control code can be simulated several orders of magnitude faster than with HIL testing (which is also available) ▪ Both complex MIMO controllers and elementary function blocks can be imported 	<ul style="list-style-type: none"> ▪ Simulation results ▪ Controller export according to IEC 61131-10 (PLCOpen XML) is planned
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Enables industrial controllers in IDA based physical system models for energy systems, buildings, and tunnels ▪ No manual interpretation of simulated control behavior has to be done for industrial implementation of developed controller since PLC control code can be used directly in the simulator – less error-prone development process 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Available for Windows ▪ Requires the open source Beremiz IDE for IEC 61131-3 model authoring 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Industry 	
Provider:	<ul style="list-style-type: none"> ▪ EQUA Simulation AB 	
Contact point:	<ul style="list-style-type: none"> ▪ Per Sahlin (EQUA) 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Commercial license 	
<i>Latest update: 3 December 2018</i>		